## ■ V.Motion Detecting Device

# Micro Switch

Z15 Series

V Series

VAP Series

**Certification Details** 

Z15 Series**(** 

V Series ( chius chi

Motion Detecting Device

> Micro Switch

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### **Specifications**

CONTACT ARRANGEMENT			1a+1b			
MATERIAL		Ag AlLoy				
CONTACT	& CONTACT D	ISTANCE			Z15G: 0.5mm	Z15H: 0,25mm
INSULATIO	N RESISTANCI	<b>E</b>		100M <sub>Q</sub> 500VDC		
CONTACT	RESISTANCE			$50 \text{m} \Omega$ or lower		
					15A 8VDC	
		RESISTIVE	15A(10) 125VAC		15A 14VDC	
		LOAD	15A(10) 250VAC		6(2)A 30VDC	
			10A 500VAC		0.5A 125VDC	
					0.25A 250VDC	
	NON		NORMINAL OPEN N	10	MORMINAL CLOSE NC	
	LOAD	LAMB	1.5A 125VAC	1.5A 8VDC	3A 125VAC	3A 8VDC
		LAMP LOAD	1,25A 250VAC	1.5A 14VDC	2.5A 250VAC	3A 14VDC
			0.75A 500VAC	1.5A 30VDC	1.5A 500VAC	3A 30VDC
				0.5A 125VDC		0.5A 125VDC
COATACT				0.25A 250VDC		0.25A 250VDC
RATING					15A 8VDC	_
			15(10)A 125VAC		10A 14VDC	
		INDUCTIVE	15(10)A 250VAC		5(1)A 30VDC	
		LOAD	6A 500VAC		0.05A 125 VDC	
	INDUCTIVE				0.03A 250VDC	
	LOAD		NORMINAL OPEN NO		MORMINAL CLOSE NC	
		MOTOR	2,5A 125VAC	2.5A 8VDC	5A 125VAC	5A 8VDC
		MOTOR LOAD	1.5A 250VAC	2.5A 14VDC	3A 250VAC	5A 14VDC
		LUAD	0.75A 500VAC	2,5(1)A 30VDC	1.5A 500VAC	5(1)A 30VDC
				0.05A 125VDC		0.05A 125VDC
				0.03A 250VDC		0.03A 250VDC
MINI CUIDDY CUIDDENT		NORMINAL OPEN N	10	MORMINAL CLOSE	NC	
MIN. CURRY CURRENT		15A		30A		

- $\bullet$  The values in the blanks are ratings of Z15H type switch. The Z15H type switch has AC ratings of 125 V and 250 V.
- The aforementioned values are steady-state current values.
- The inductive load has a power factor of 0.4 or more (AC), and a time constant of 7 m/s or less (DC).
- The inrush current is ten times larger than steady-state current in the lamp load, and six times, in the motor load.

OPERATING SPEED		0.01mm/sec $\sim$ 0.5m/sec
ODEDATING EDECUENCY	ELECTRICAL	Min. 20 / Min.
OPERATING FREQUENCY	MECHANICAL	Min. 240 / Min.
	NONE CONTINUES IS TERMINAL	Z15G: 1000VAC 1Min,
DIELETION OTDENOTA	NON CONTINROUS TERMINAL	Z15H: 600VAC 1Min.
DIELETICAL STRENGTH	TERMINAL & EARTH	2000VAC 1Min,
	TERMINAL & NON CHARGED METAL PART	2000VAC 1Min,
EVENTED LIFE	ELECTRICAL	Min. 500,000
EXPECTED LIFE	MECHANICAL	Min. 20,000,000
VIBRATION	MALFUNCTION DURABILITY	10Hz~55Hz Durable Amplitude 1,5mm
0110014	MALFUNCTION DURABILITY	Max, 30G
SHOCK	MECHANICAL DURABILITY	Max. 100G
ELECTRIC SHICK PROTECTION		Class 1
AMBIENT TEMPERATURE		-25°C~+80°C(WITH NO ICING)
AMBIENT HUMIDITY		35%~85% RH
TORQUE		1,2N · m (12,24kgf · cm)

<sup>\*\*</sup> This is the case for the push-button type (The values are for the actuator for the lever type).
In the types other than the push-button type, the mechanical life is 10 million times, and the operating error is 1 ms or less.



Z15G-01B	Z15G-010B	Z15G-10B	Z15G-03B
MACON Z-15001-5	Model and the second	MAGON Z-155N-S	PORON 2-1500A-8
Z15G-030B	Z15G-031B	Z15G-05B	Z15G-052B
Moon is the second	Mod remains	1/4/201 Z-15/30 S	Mood Justine
Z15G-063B	Z15G-062B	Z15G-061B	Z15G-06B
MACON 2.45000.5	I/ACON TABLES	NACON STATEMENT	MCOII 2.150ks
Z15H-060B	Z15H-08B	Z15G-09B	Z15G-091B
ANOTHER PROPERTY.	Incel 1.5861	No.	MCOI LINE
Z15G-092B	Z15G-07B	Z15G-073B	
	I ACON LABORAL DE LA CONTRACTOR DE LA CO	IACOU Z-150/IT-9	

Motion Detecting Device

Micro Switch

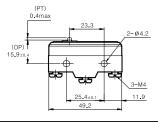
# \*5-1\_마이크로 스위치변형수정 2011.7.14 4:47 PM 페이지 V -4 은광문자사 2438-670-c 2540DPI 175LPI CMVK

#### **Dimension** Unit: mm

### Z15G-01B

KS: Z4G1P01B





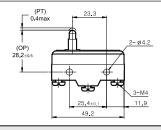


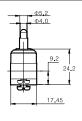
OF	250~350gf(2.45~3.43N)
RF	114gf(1,12N)
PT	0.4mm
ОТ	0.13mm
MD	0.05mm
OP	15.9±0.4mm

### Z15G-010B

KS: Z4G1P03B





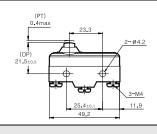


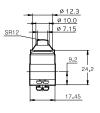
OF	250 ~ 350gf(2,45 ~ 3,43N)
RF	114gf(1,12N)
PT	0.4mm
ОТ	1,6mm
MD	0.05mm
OP	28,2±0,5mm

### Z15G-10B

KS: Z4G1P09B





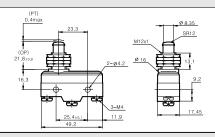


OF	250 ~ 350gf(2,45 ~ 3,43N)
RF	114gf(1,12N)
PT	0.4mm
ОТ	1,6mm
MD	0.05mm
OP	21.5±0.5mm

### Z15G-03B

KS: Z4G1P05B



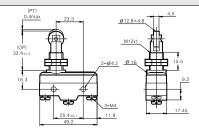


OF	250 ~ 350gf(2.45 ~ 3.43N)
RF	114gf(1,12N)
PT	0.4mm
ОТ	5,5mm
MD	0.05mm
OP	21,8±0,8mm

### Z15G-030B

KS: Z4G1P07B

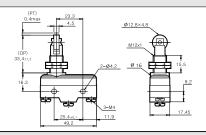




OF	250 ~ 350gf(2.45 ~ 3.43N)
RF	114gf(1,12N)
PT	0.4mm
OT	3.58mm
MD	0.05mm
OP	33,4±1,2mm

### Z15G-031B



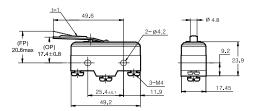


OF	250 ~ 350gf(2.45 ~ 3.43N)
RF	114gf(1,12N)
PT	0.4mm
ОТ	3,58mm
MD	0.05mm
OP	33.4±1.2mm

### Z15G-05B

KS: Z4G1R01B



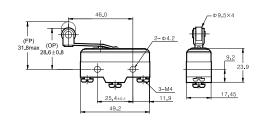


OF	141gf(1,38N)
RF	14gf(0.14N)
OT	1,6mm
MD	1,3mm
FP	20,6mm
OP	17.4±0.8mm

### Z15G-052B

KS: Z4G1R03B



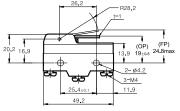


OF	141gf(1,38N)
RF	14gf(0.14N)
ОТ	1,6mm
MD	1,3mm
FP	31,8mm
OP	28.6±0.8mm

### Z15G-063B

KS: Z4G1L05B



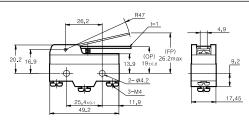




OF	160gf(1,57N)
RF	28gf(0,27N)
ОТ	2,0mm
MD	1.0mm
FP	24,8mm
OP	19.0±0.8mm

### Z15G-062B



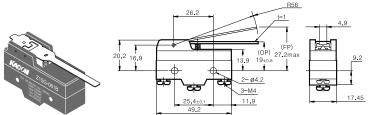


OF	95gf(0.95N)
RF	18gf(0,18N)
ОТ	4.2mm
MD	0.95mm
FP	26,2mm
OP	19.0±0.8mm

Motion Detecting Device

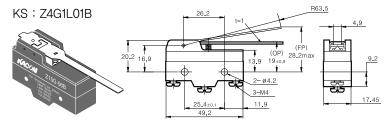
Micro Switch

### Z15G-061B



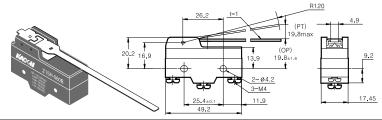
OF	80gf(0,78N)
RF	15.5gf(0.15N)
ОТ	4.8mm
MD	1,12mm
FP	27.2mm
OP	19.0±0.8mm

### Z15G-06B



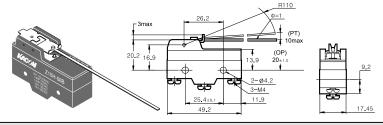
OF	70gf(0,69N)
RF	14gf(0.14N)
ОТ	5,6mm
MD	1,27mm
FP	28,2mm
OP	19.0±0.8mm

### Z15H-060B



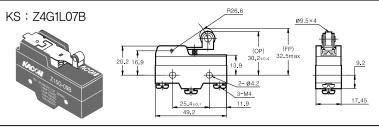
OF	6gf(58,8mN)
RF	0.5gf(4.90mN)
PT	19.8mm
ОТ	10,0mm
MD	2,0mm
OP	19.8±1.6mm

### Z15H-08B



OF	4gf(39,2mN)
RF	0.3gf(2,94mN)
PT	10,0mm
ОТ	6.0mm
MD	3.0mm
OP	20.0±1.0mm

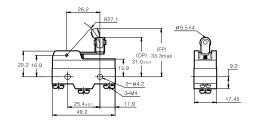
### Z15G-09B



OF	160g(1.57N)
RF	42g(0,41N)
ОТ	2.4mm
MD	0.5mm
FP	32,5mm
OP	30.2±0.4mm

### Z15G-091B

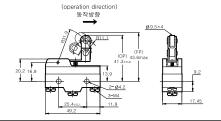




OF	170gf(1,67N)
RF	42gf(0,41N)
PT	2.4mm
ОТ	0,51mm
MD	33,3mm
OP	31.0±0.4mm

### Z15G-092B



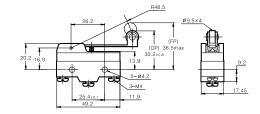


OF	170gf(1,67N)
RF	42gf(0,41N)
PT	2,4mm
ОТ	0,51mm
MD	43,6mm
OP	41.3±0.8mm

### Z15G-07B

KS: Z4G1L03B

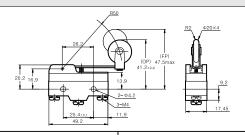




OF	100gf(0,98N)
RF	22gf(0,22N)
PT	4.0mm
OT	1,02mm
MD	36,5mm
OP	30,2±0,8mm

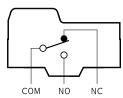
### Z15G-073B





OF	100gf(0,98N)
RF	21gf(0,21N)
PT	4.0mm
ОТ	1,6mm
MD	47.5mm
OP	41,2±0,8mm
	•

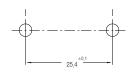
### **DIAGRAM**

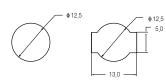


COM: COMMON TERMINAL NO : NNORMAL OPEN TERMINAL

NC: NORMAL CLOSE TERMINAL

### **PANEL CUT OUT**





Motion Detecting Device

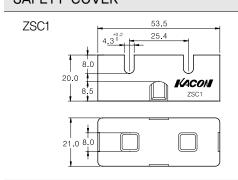
Micro Switch

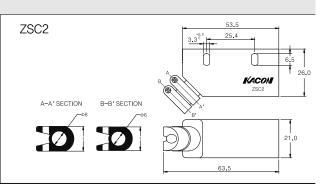
### Glossary

Definition of operating characteristics	Category	Abbr.	Term	Unit	Definition
		Force required for operation	OF	g, kg g-mm	Force on the actuator required for the motion from the free position to the operating position
	Force	Restoring force	RF	g, kg g-mm	Force on the actuator required for the motion from the operating limit position to the restoring position
		Force required for entire motion	TF	g, kg g-mm	Force on the actuator required for the motion from the operating position to the operating limit position
PP OF TRANSPORTED TO THE TRANSPO		Motion to the operating position	PT	mm, deg	Distance or angle from the free position of the actuator to the operating position
	Motion	Motion after operation	OT	mm, deg	Distance or angle from the operating position of the actuator to the operating limit position
Center of the switch		Hysteresis distance	MD	mm, deg	Distance or angle from the operating position of the actuator to the restoring position
mounting hole		Total motion	TT	mm, deg	Distance or angle from the free position of the actuator to the operating limit position
TTP		Free position	FP	mm, deg	The position of the operating part when no force is applied from outside
		Operating position	OP	mm, deg	The position of the actuator when the external force is applied to the actuator and the moving contact reverses from the free position
	Position	Restoring position	RP	mm, deg	The position of the actuator when the external force to the actuator is reduced and the moving contact reverses from the operating position to the free position
		Operating limit position	TTP	mm, deg	The position of the actuator when the actuator reaches the actuator stop position

## Option

## SAFETY COVER







### Per-Caution

#### Electrical precautions

#### Electrical conditions

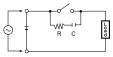
- · Check the rating because the contact has different breaking capacities for AC and DC.
- · For microvoltage and microcurrent, use the contact for microload.
- · Check the inrush current, steady-state current and inrush time.
- Measure the contact resistance at DC 6 V~DC 8 V and 1A (Comply with the voltage drop method for the microcurrent).
- •The difference between the steady-state current and inrush current may vary according to the load type. Check the inrush current value.

#### • The ratings are based on the following conditions.

- · Inductive load: power factor 0.4 or more (AC), time constant 7 ms or less (DC)
- Lamp load: Inrush current≥10×Steady-state current
- Motor load: Inrush current≥6× Steady-state current

#### Notes for the circuit

· In the inductive load breaking circuit, the surge and inrush current at the opening/closing of the circuit may cause contact problems. Therefore, it is desirable to insert a protection circuit as follows,



Normally used for DC circuits. A resistor of several ohms is required.

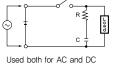
When used for AC circuit, the load must be small.

R: Tens~100 Ω

C: 0.05~0.1 uF

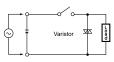


Used only for DC circuits. Select a diode with sufficient margin to the inverse withstand voltage.



R: Tens of ohms

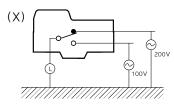
C: 0.1~0.2 uF



Used both for AC and DC circuits.

Select a varistor that is 15 times higher than the power supply voltage.

- · Do not connect different polarities and types of power to one switch contact.
- Do not apply the voltage between contacts (This causes the mixed contact and contact weld).



#### Application to the electronic circuits (low voltage and current)

- 1. The microswitch generates bouncing and chattering between contacts when it is switched on/off. This causes troubles, including noises and wrong pulses, to the electronic circuits or acoustic devices.
- 2. When bouncing and chattering cause problems, studies are required to provide an absorption circuit in addition to the CR circuit.
- 3. In the areas that require high contact reliability, the Ag contacts, which have been widely used, are hardly used. Au contacts have high performances for microvoltage and microcurrent.

### Mechanical precautions

#### Mechanical conditions

- · Select the actuator according to the operating method.
- Do not apply excessive force to the actuator.
- · Check the switching speed and frequency.
  - 1) If the switching speed is too slow and unstable, poor contact or contact weld may occur.
  - 2) If the switching speed is too high, switching may not be completed.

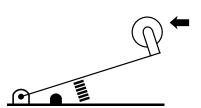
Motion Detecting Device

> Micro Switch

I imit Switch

#### Precautions

- The operating method, cam or dog type, frequency, motion after switching significantly influence the product life and accuracy. Use the cams or dogs that have general shapes.
- Do not allow the load to one side of the switch actuator, and prevent the partial wear.
- Adjust the actuator so that it does not pass beyond OT. The proper operating stroke is 70 %~100 % of the standard OT.
- If OT passes beyond the limit, it may cause failure,
- Use the switch considering the characteristics of the actuator. In the case of the roller arm lever, do not apply force in the arrowed direction in the figure.
- Avoid the modification of the operating position by processing the actuator.



#### Mounting precautions

#### Environment

- If the switch is not waterproof and sealed, do not use the product in the environment where oil or water scatters or bursts. Use the protective cover to avoid direct exposure to the liquid. A limit switch is more proper for this case than the standard switch.
- Contact us when using the limit switch outside or with special cutting oil so that the deterioration of the switch material is expected.
- Place the switch on the place where it is not directly exposed to the processing waste or dusts, Protect the actuator and switch body from the cutting waste or foreign matters.

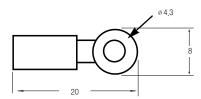
- Do not use the switch in the temperature and air conditions other than specified. The allowable ambient temperature varies according to the product type (Check the product specifications).
   In the case of abrupt thermal change, the heat impact deforms the switch and causes failure.
- When mounting the switch in the place where operating errors or accidents may happen in the normal operator or equipment conditions, additional measures are required.

### • Precautions for the panel mounting type

- Use M4 screws for fixing. Mount the product firmly using flat or spring washers, The proper tightening torque is  $12\sim15~\text{kgf}\cdot\text{cm}$  (1.18 $\sim$ 1.47 N · m).
- The proper tightening torque for the hexagonal nut of the actuator is 50 kgf · cm (4.9 N · m).
- When mounting the panel mounting pushbutton type on the side using screws, remove the hexagonal nuts from the actuator part.
- For the connection with lead terminals, use crimp terminals at a tightening torque of  $8{\sim}12$  kgf · cm (0.78 ${\sim}1.18$  N · m). (Recommended wire spec.: VCT 1.25 mm² twowire, three-wire)

#### Precautions for the drip-proof type

- Do not soak the product in oil because this product is not completely oil—tight,
- Avoid using this product in the condition where temperature abruptly changes,



\* Specifications and materials can change without prior notice.



# V Series



### **Specification**

CONTACT	ARRANGEMEN	IT	1a+1b				
MATERIAL			Ag AlLoy				
CONTACT	& CONTACT D	DISTANCE	0.5mm				
INSULATIO	N RESISTANC	E	100M <i>Q</i> 500VDC				
CONTACT	RESISTANCE		50mΩ				
			NORMINAL OPE	N NO	MORMINAL CLO	SE NC	
			15A 125VAC	10A 8VDC	15A 125VAC	15A 8VDC	
		RESISTIVE	10A 250VAC	5A 14VDC	15A 250VAC	15A 14VDC	
		LOAD		2A 30VDC		10A 30VDC	
		LUAD		0.5A 125VDC		0.6A 125VDC	
	NON			0,25A 250VDC		0.3A 250VDC	
	INDUCTIVE	LAMP LOAD	1.5A 125VAC	1.5A 8VDC	3A 125VAC	4A 8VDC	
	LOAD		1.0A 250VAC	1.5A 14VDC	2A 250VAC	4A 14VDC	
				1.0A 30VDC		4A 30VDC	
				0.1A 125VDC		0.1A 125V	
COATACT				0,05A 250VDC		0.05A 250VDC	
RATING		INDUCTIVE LOAD	10A 125VAC	8A 8VDC	10A 125VAC	10A 8VDC	
			6A 250VAC	4A 14VDC	10A 250VAC	10A 14VDC	
				1.5A 30VDC		6A 30VDC	
				0,05A 125VDC		0.6A 125VDC	
	INDUCTIVE			0.03A 250VDC		0.3A 250VDC	
	LOAD		2A 125VAC	2,5A 8VDC	4A 125VAC	6A 8VDC	
		MOTOR	1A 250VAC	2.5A 14VDC	3A 250VAC	6A 14VDC	
		MOTOR LOAD		1.5A 30VDC		4A 30VDC	
		LOAD		0.05A 125VDC		0.1A 125VDC	
				0.04A 250VDC		0.05A 250VDC	
MINI OURDAY OURDENIT		NORMINAL OPEN	NO	MORMINAL CLOS	SE NC		
MIN. CURRY CURRENT		15A		30A			

- The aforementioned values are steady-state current values.
- The inductive load has a power factor of 0.4 or more (AC), and a time constant of 7 m/s or less (DC).
- The inrush current is ten times larger than steady-state current in the lamp load, and six times, in the motor load.

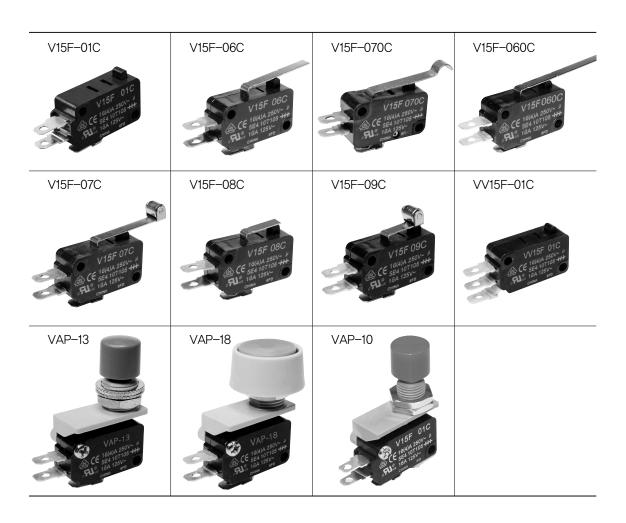
OPERATING SPEED		0.1mm/sec $\sim$ 0.5m/sec		
OPERATING FREQUENCY	ELECTRICAL	Max. 20 / Min.		
OPERATING FREQUENCY	MECHANICAL	Max. 60 / Min.		
DIELETICAL STRENGTH	NON CONTINROUS TERMINAL	1,000VAC 1Min.		
DIELETICAL STRENGTH	TERMINAL & NON CHARGED METAL PART	1,500VAC 1Min.		
EXPECTED LIFE	ELECTRICAL	Min. 100,000		
EXPECTED LIFE	MECHANICAL	Min. 1,000,000		
내VIBRATION		10~55Hz(Durable Amplitude 1,5mm)		
<b>Ч</b> SHOCK		30G		
AMBIENT TEMPERATURE		-25°C ∼ +80°C		
AMBIENT HUMIDITY		35%~80% RH		

<sup>\*</sup> The material and the specification of the product can be changed without notice for better quality.

Motion Detecting Device

> Micro Switch



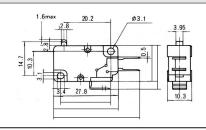


### **Dimension**

 $\mathsf{Unit}:\mathsf{mm}$ 

### V15F-01C



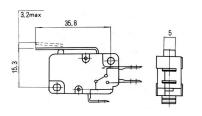


PT	1,7mm MAX.
MD	0.4mm MAX.
ОТ	0.8mm MIN.
OP	14.7±0.6mm

### V Series

### V15F-06C

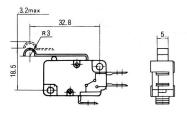




PT	3,2mm MAX,		
MD	1,2mm MAX.		
ОТ	1,2mm MIN,		
OP	15.3±1.2mm		

### V15F-070C

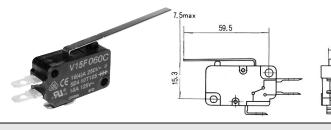




PT	3,2mm MAX.
MD	1,2mm MAX.
ОТ	1,2mm MIN.
OP	15.5±1,2mm

Motion

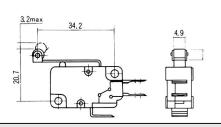
### V15F-060C



PT	7.5mm MAX.
MD	2,2mm MAX.
ОТ	2,2mm MIN.
OP	15.3±2.6mm

### V15F-07C

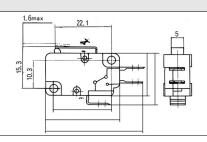




PT	3,2mm MAX.		
MD	1,2mm MAX.		
ОТ	1,2mm MIN.		
OP	20.7±1.2mm		

### V15F-08C





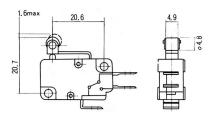
PT	1,6mm MAX.		
MD	0.5mm MAX.		
ОТ	0.8mm MIN.		
OP	15.3±0.8mm		

Detecting Device

Micro Switch

### V15F-09C

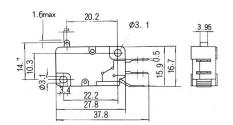




PT	1,6mm MAX.
MD	0.5mm MAX.
ОТ	0.8mm MIN.
OP	20.7±0.8mm

### VV15F-01C

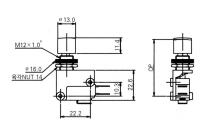




-	PT	1,6mm MAX,		
	MD	0.4mm MAX.		
-	ОТ	0.8mm MIN.		
-	OP	14.7±0.6mm		

### VAP-13



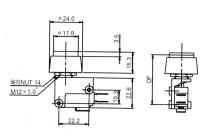


### · Button Color K, B, R, G, Y

PT	1,6mm MAX.		
MD	0.4mm MAX.		
OT	0.8mm MIN.		
OP	14.7±0.6mm		

## VAP-18





### · Button Color K, B, R, G, Y

PT	1,6mm MAX.		
MD	0.4mm MAX.		
ОТ	0.8mm MIN.		
OP	14.7±0.6mm		

### V Series

### Glossary

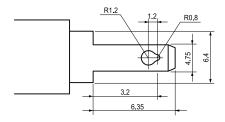
Definition of operating characteristics	Category	Abbr.	Term	Unit	Definitio
	Force	Force required for operation	OF	g, kg g-mm	Force on the actuator required for the motion from the free position to the operating position
		Restoring force	RF	g, kg g-mm	Force on the actuator required for the motion from the operating limit position to the restoring position
		Force required for entire motion	TF	g, kg g-mm	Force on the actuator required for the motion from the operating position to the operating limit position
OF RT RT		Motion to the operating position	PT	mm, deg	Distance or angle from the free position of the actuator to the operating position
FP TTP P	Motion	Motion after operation	ОТ	mm, deg	Distance or angle from the operating position of the actuator to the operating limit position
Center of the switch		Hysteresis distance	MD	mm, deg	Distance or angle from the operating position of the actuator to the restoring position
mounting hole		Total motion	TT	mm, deg	Distance or angle from the free position of the actuator to the operating limit position
TTP RE TTP	Position	Free position	FP	mm, deg	The position of the operating part when no force is applied from outside
		Operating position	OP	mm, deg	The position of the actuator when the external force is applied to the actuator and the moving contact reverses from the free position
		Restoring position	RP	mm, deg	The position of the actuator when the external force to the actuator is reduced and the moving contact reverses from the operating position to the free position
		Operating limit position	TTP	mm, deg	The position of the actuator when the actuator reaches the actuator stop position

Motion Detecting Device

Micro Switch

Limit Switch

### **Terminal**



\* Quick Connect Tab #187 / Soldering

